

More matrix algebra

let $\psi = \sum_{i=1}^N c_i \phi_i$ $\{\phi_i\}$ is the set of N basis functions

$$\Rightarrow \tilde{A} = \langle \psi | \hat{A} | \psi \rangle = \sum_{i=1}^N \sum_{j=1}^N c_i^* A_{ij} c_j \quad \sum_{i=1}^N c_i^* c_i = 1 \quad \Psi \text{ normal}$$

$$A_{ij} = \langle \phi_i | \hat{A} | \phi_j \rangle = \text{matrix element}$$

In matrix notation

$$\bar{A} = \tilde{c}^+ \tilde{A} \tilde{c} \quad \tilde{c}^+ \tilde{c} = 1$$

where

$$\tilde{c} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_N \end{pmatrix} \text{ column vector} \quad \tilde{c}^+ = \begin{pmatrix} c_1^* & c_2^* & \dots & c_N^* \end{pmatrix} \text{ row vector}$$

Determinants

$$|\tilde{A}| = \sum_i (-1)^{i+j} a_{ij} |A_{ij}|$$

For a 2x2 matrix:

$$|\tilde{A}| = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{21}a_{12}$$

For a 3x3 matrix: label each matrix element in the following way (in your mind)

$$\tilde{A} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ (+) & (-) & (+) \\ a_{21} & a_{22} & a_{23} \\ (-) & (+) & (-) \\ a_{31} & a_{32} & a_{33} \\ (+) & (-) & (+) \end{pmatrix}$$

The +/- are the signs of the cofactors

Can expand the determinant along any row or column. Using the first row:

$$\begin{aligned} |\tilde{A}| &= a_{11}(-1)^{1+1} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} + a_{12}(-1)^{1+2} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13}(-1)^{1+3} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} \\ &\Rightarrow |\tilde{A}| = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} \end{aligned}$$

For a diagonal matrix where all off-diagonal elements are zero:

$$\tilde{A} = \begin{pmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{pmatrix} \Rightarrow |\tilde{A}| = a_{11}a_{22}a_{33}$$

Further properties of determinants:

$$\left| \tilde{A}^T \right| = \left| \tilde{A} \right|$$

$$\left| \tilde{A}^* \right| = \left| \tilde{A} \right|^*$$

$$\left| \tilde{A}^+ \right| = \left| \tilde{A}^* \right| = \left| \tilde{A} \right|^*$$

More Theorems

- 1.) A Hermitian matrix \mathbf{H} has “real” eigenvalues
- 2.) A Hermitian matrix can be diagonalized by a unitary transformation; that is, there is a matrix \mathbf{S} such that:

$$\tilde{\mathbf{S}}\tilde{\mathbf{H}}\tilde{\mathbf{S}}^{-1} = \tilde{\mathbf{D}}$$

- 3.) $\left| \tilde{\mathbf{S}}\tilde{\mathbf{H}}\tilde{\mathbf{S}}^{-1} \right| = \left| \tilde{\mathbf{D}} \right|$

This means the eigenvalues of \mathbf{H} and $\mathbf{S}\mathbf{H}\mathbf{S}^{-1}$ are equal; that is, the physical content is unaffected by the unitary transformation

- 4.) If two Hermitian matrices \mathbf{H}_1 and \mathbf{H}_2 commute then they can be simultaneously diagonalized (no proof give). This means there is a \mathbf{S} such that:

$$\tilde{\mathbf{S}}\tilde{\mathbf{H}}_1\tilde{\mathbf{S}}^{-1} = \tilde{\mathbf{D}}_1$$

$$\tilde{\mathbf{S}}\tilde{\mathbf{H}}_2\tilde{\mathbf{S}}^{-1} = \tilde{\mathbf{D}}_2$$

Solution of the eigenvalue problem using complete sets

= Matrix Mechanics

$$\hat{M}\psi_i = m_i\psi_i \quad \text{or} \quad \hat{M}\psi = m\psi \quad (1) \quad \text{Could take } \mathbf{M} = \mathbf{H}; m = E, \text{ etc.}$$

In the Schrodinger approach, \mathbf{M} is a differential equation which we solve for the eigenfunctions and eigenvalues. These can involve relatively hard calculus methods.



In the Heisenberg approach, \mathbf{M} is a matrix which we solve for the eigenvectors and eigenvalues by relatively easy linear algebra methods.



Either approach is valid and give the same answers.

Let $\{\Omega_i\}$ be a convenient complete basis set $\{\Omega_i\}$ in the space of the problem. We need a complete set so all the standard problems covered in C374a are useful. These include the particle-in-a box wave functions, harmonic oscillator functions, rigid-rotor functions, H-atom orbitals, etc.

Which do you choose? It depends on the problem. If the Hamiltonian for example is a distorted particle-in-a box type problem, use a normal particle-in-a box basis set to construct the matrix operators.

In general:

$$\langle \Omega_i | \Omega_j \rangle = \delta_{ij} \quad (\text{orthonormal})$$

Write: $\psi = \sum_{i=1}^N c_i \Omega_i$ (2) $N = \text{infinity to be rigorous; in practice it isn't.}$

Substitute (2) into (1).

$$\Rightarrow \sum_{i=1}^N c_i \hat{M} \Omega_i = m \left(\sum_{i=1}^N c_i \Omega_i \right)$$

Multiply by Ω_k^* and integrate. ($k = 1, 2, 3, \dots, N$)

$$\therefore \sum_{i=1}^N c_i \underbrace{\langle \Omega_k | \hat{M} | \Omega_i \rangle}_{M_{ki}} = m \sum_{i=1}^N c_i \underbrace{\langle \Omega_k | \Omega_i \rangle}_{\delta_{ki}} = m c_k$$

Matrix elements in $\{\Omega_i\}$;
known

$$\therefore \sum_{i=1}^N M_{ki} c_i = m c_k$$

$$\Rightarrow \sum_{i=1}^N [M_{ki} - m \delta_{ki}] c_i = 0 ; (k = 1, 2, 3, \dots, N) \quad (3)$$

(3) Is a set of N simultaneous homogenous linear equations in N unknowns:
 $\{c_i\}$ $i = 1, 2, 3, \dots, N$ once $\{m\}$ are known.

A trivial solution, $c_i = 0$ for all i will satisfy (3) (but not us).

A non-trivial solution exist only if the determinant of the coefficients of the unknowns is zero

$$\left| M_{ki} - m\delta_{ki} \right| = 0 \quad (4)$$

Expanding (4) out yields a polynomial of degree N for m since the M_{ki} are known.

→ N roots: m_i $i=1, 2, 3, \dots, N$

Let's see what these results look like in matrix notation.

(3) Written in long hand for $k=1,2,3,\dots,N$

$$k = 1: M_{11}c_1 + M_{12}c_2 + M_{13}c_3 + \dots + M_{1N}c_N = mc_1$$

$$k = 2: M_{21}c_1 + M_{22}c_2 + M_{23}c_3 + \dots + M_{2N}c_N = mc_2$$

$$k = 3: M_{31}c_1 + M_{32}c_2 + M_{33}c_3 + \dots + M_{3N}c_N = mc_3$$

⋮

$$k = N: M_{N1}c_1 + M_{N2}c_2 + M_{N3}c_3 + \dots + M_{NN}c_N = mc_N$$

This is the same as: $\tilde{M}\tilde{c} = m\tilde{c}$ eigenvalue problem in matrix form where:

$$\tilde{M} = \begin{pmatrix} M_{11} & M_{12} & M_{13} & \dots & M_{1N} \\ M_{21} & M_{22} & M_{23} & \dots & M_{2N} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ M_{N1} & M_{N2} & M_{N3} & \dots & M_{NN} \end{pmatrix}$$

N x N square matrix

$$\tilde{c} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_N \end{pmatrix}$$

N x 1 column matrix
or column vector