

6.3 Distributed Random Loading Due to Wind

Multiple Discrete Loads

Consider a randomly varying quantity $z(t)$ made up of two components, $x(t)$ and $y(t)$,

$$z(t) = x(t) + y(t)$$

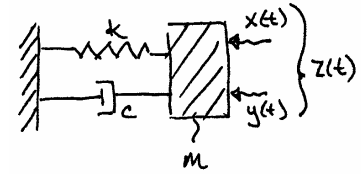


Fig. 6.4 Multiple loads

The autocorrelation function of the combined input, $R_z(\tau)$, is:

$$\begin{aligned} R_z(\tau) &= \langle z(t)z(t+\tau) \rangle \\ &= \langle [x(t) + y(t)][x(t+\tau) + y(t+\tau)] \rangle \\ &= \langle x(t)x(t+\tau) + x(t)y(t+\tau) + y(t)x(t+\tau) + y(t)y(t+\tau) \rangle \end{aligned}$$

Thus, $R_z(\tau) = R_{xx}(\tau) + R_{xy}(\tau) + R_{yx}(\tau) + R_{yy}(\tau)$

In which $R_{xx}(\tau)$ and $R_{yy}(\tau)$ are the autocorrelation functions of signals x and y and:

$$\begin{aligned} R_{xy}(\tau) &= \langle x(t)y(t+\tau) \rangle \\ R_{yx}(\tau) &= \langle y(t)x(t+\tau) \rangle \end{aligned}$$

the *cross-correlation* or *cross-covariance* functions.

The correlation function of a combined signal is determined by the autocorrelations of the components and by their cross-correlations. The cross-correlation will be zero only if the components $x(t)$ and $y(t)$ are completely uncorrelated or unrelated.

When a signal consists of more components, so that:

$$z(t) = x_1(t) + x_2(t) + x_3(t) + \dots + x_n(t)$$

The autocorrelation $R_z(\tau)$ is:

$$\begin{aligned} R_z(\tau) &= R_{11}(\tau) + R_{12}(\tau) + R_{13}(\tau) + \dots + R_{1n}(\tau) + \\ &\quad R_{21}(\tau) + R_{22}(\tau) + R_{23}(\tau) + \dots + R_{2n}(\tau) + \\ &\quad R_{31}(\tau) + R_{32}(\tau) + R_{33}(\tau) + \dots + R_{3n}(\tau) \end{aligned}$$

which can be written as a double sum: $R_z(\tau) = \sum_r \sum_s R_{rs}(\tau)$

or as a correlation matrix: $[R_z] = [R_{ij}]$

$$[R_z] = \begin{bmatrix} R_{11} & R_{12} & \cdots & R_{1n} \\ R_{21} & R_{22} & \cdots & R_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ R_{n1} & R_{n2} & \cdots & R_{nn} \end{bmatrix}$$

Properties of cross-correlations of stationary processes:

$$R_{xy}(-\tau) = \langle x(t)y(t-\tau) \rangle = \langle y(t)x(t+\tau) \rangle = R_{yx}(\tau)$$

$$R_{yx}(-\tau) = \langle y(t)x(t-\tau) \rangle = \langle x(t)y(t+\tau) \rangle = R_{xy}(\tau)$$

$$R_{xx}(-\tau) = \langle x(t)x(t-\tau) \rangle = \langle x(t)x(t+\tau) \rangle = R_{xx}(\tau)$$

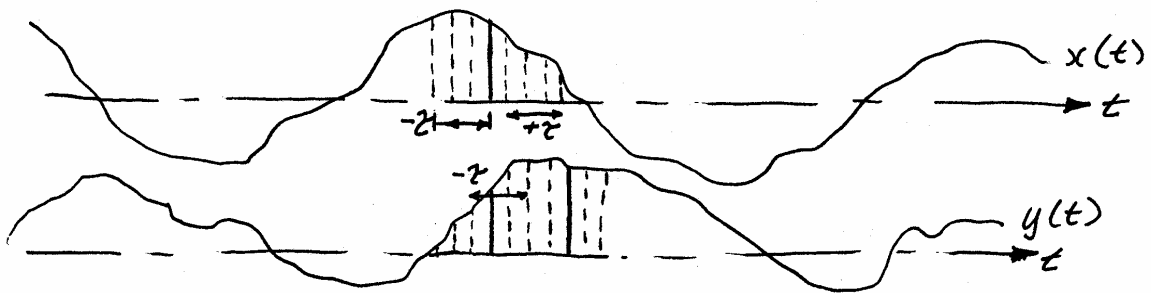


Fig. 6.5 Time history of two signals, $x(t)$ and $y(t)$

There is no relation between $R_{xy}(\tau)$ and $R_{xy}(-\tau)$; $R_{xy}(\tau)$ and $R_{yx}(\tau)$ are in general, unrelated.

$R_{xy}(\tau)$ and $R_{yx}(\tau)$ do not necessarily have their maximum values at $\tau=0$.

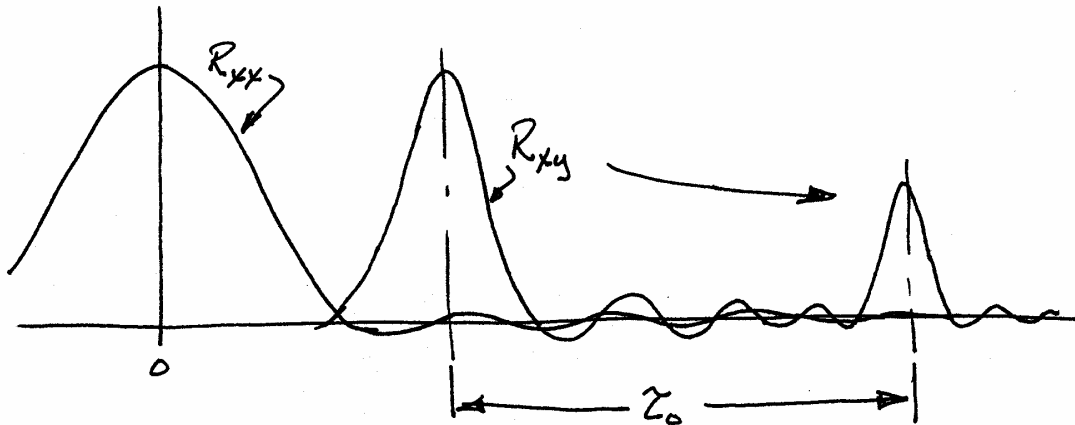


Fig. 6.6 Auto and Cross Correlation Functions

The distance between two peaks determines the average time delay between two processes, e.g. wind speed and wind pressure.

Covariance

When $\tau = 0$, $R_{xy}(0) = \langle x(t)y(t) \rangle = \sigma_{xy}^2$, which is covariance. This is the measure of the extent to which two random variables, x, y are correlated. In they are completely independent, $\sigma_{xy}^2 = 0$ and also $R_{xy} = R_{yx} = 0$.

Correlation Coefficient

A dimensionless form of covariance

$$R = \frac{\sigma_{xy}^2}{\sigma_x \sigma_y} \leq 1.0$$

or, when $\sigma_x = \sigma_y = \sigma$, $R = \sigma_{xy}^2 / \sigma^2$

When $R = 1$, the process is fully correlated and if $R = 0$, the process is completely uncorrelated.

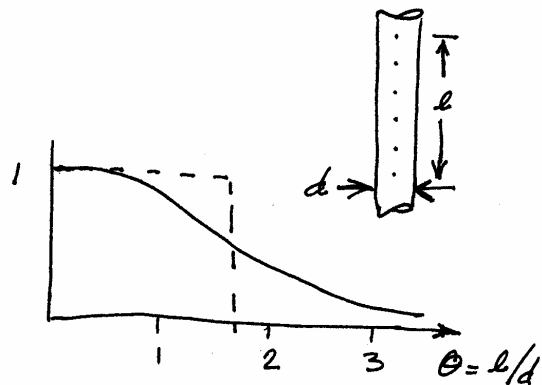


Fig. 6.7 Correlation Coefficient

The correlation length, L , can measure the span-wise correlation and is defined as:

$$\frac{L}{d} = \int_0^{\infty} R(\theta) d\theta \text{ in numbers of diameters, } d.$$

Further useful relationships are:

$$\begin{aligned} |R_{xy}(\tau)|^2 &\leq R_x(0)R_y(0) \\ R_{xy}(\tau) &\leq \frac{1}{2}[R_x(0) + R_y(0)] \end{aligned}$$

The *correlation function coefficient*, (normalized cross-covariance or cross-correlation function), is, with zero means,

$$\rho_{xy}(\tau) = \frac{R_{xy}(\tau)}{\sqrt{R_x(0)R_y(0)}} = \frac{R_{xy}(\tau)}{\sigma_x\sigma_y}$$

The area beneath the curve is a measure of the time over which the processes are correlated,

$T = \int_0^{\infty} \rho_{xy}(\tau) d\tau$ and is called the *time scale*. In the case of wind, T is the time scale of turbulence, determined from ρ_{xx}, ρ_{yy} respectively.

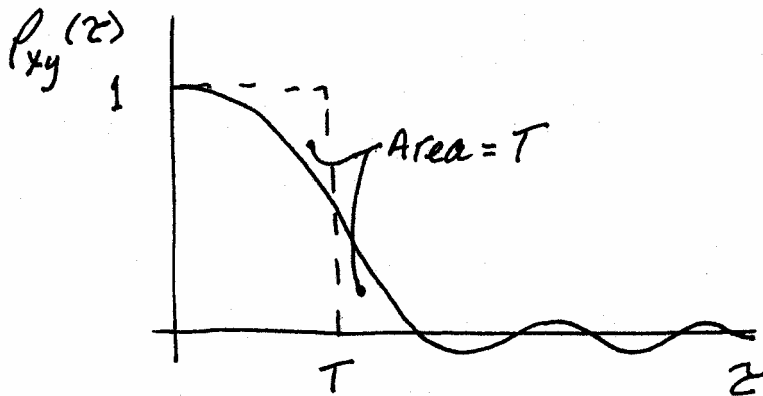


Fig. 6.8 Effective time scale

A more complete picture of the process with respect to its frequency content can be obtained from "cross-correlations" and "cross-spectral densities". In most cases, we can describe the process in a simplified way through the spectral density and the correlation coefficient, which can be replaced with the correlation length.

i.e. Local Spectra x Correlation Length